Soft Computing Applications (IT 60108)

Spring, 2015-2016

Practice Sheet-II

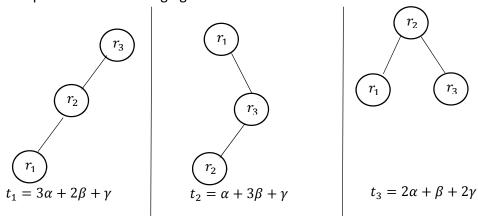
A. Introduction to Optimization Problems and Solving Techniques

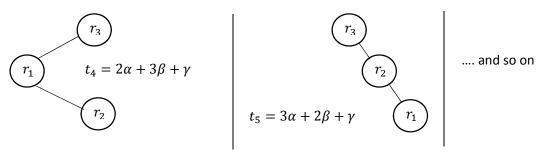
1.	An inte	ger programming problem may be
	(a)	Unconstrained optimization.
	(b)	Constrained optimization.

- (c) None of the above.
- (d) All of the above.
- 2. Genetic algorithms are always guaranteed to give optimal solution.
 - (a) True.

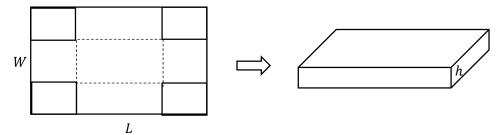
- (b) False.
- 3. Genetic algorithm is used to solve any optimization problem.
 - (a) True.
 - (b) False.
- 4. Which of the following problem cannot be solved with GA?
 - Clustering problem (for example, a number of document are given and you have to (a) group them according to some criteria, say similarity).
 - (b) Job machine assignment problem (for example, there are different machines with different throughputs and a number of different jobs with different needs of their processing times).
 - (c) Network cabling problem (a number of computers are there in geographically distributed locations and it is required to lay cable connecting them, so that anyone can connect to others).
 - (d) Matching problem (for example, given a document, it is required to find a subset of documents in Internet so that each document in the subset has at least p% score of matching)
- 5. The travelling salesman problem (TSP):
 - Define the problem. (a)
 - (b) Express the problem as an optimization problem.

- (c) Show that this problem cannot be solved in polynomial time (we say that a problem can be solved in polynomial time, if time required to solve the problem is $k.N^x$, where k and x are some positive constant and real number, respectively. For example, $2.5n^2$ or $8n^{0.5}$ etc.
- **6.** Frame the following problem as an optimization problem
 - (a) An order pair (c_i, n_i) denoting that n_i number of coins with denomination c_i .
 - (b) Given k such order pairs (i.e. number of coins with denominations).
 - (c) Given an amount say R. You have to change R in terms of minimum number of coins only.
 - (i) Identify the design parameters, objective function, constraint(s), if any in the above mentioned problem.
 - (ii) Show whether this problem can be solved in polynomial time or not. If so, how? If not, why?
- **7.** Binary search tree construction problem can be illustrated as follows:
 - Suppose, three records r_1 , r_2 and r_3 are to be stored in a computer disk. r_1 , r_2 and r_3 denotes their record numbers such that $r_1 < r_2 < r_3$.
 - (b) α, β and γ denote the probability that the records r_1 , r_2 and r_3 are to be accessed respectively such that $\alpha + \beta + \gamma = 1$.
 - (c) Five possibilities of arranging them are shown below:





- (i) Find at least three more such binary trees.
- (ii) How many search trees are possible, if n records $r_1, r_2, r_3, \dots, r_n$ are to be maintained.
- (iii) State this problem as an optimization problem identifying objective functions, constraints and all design variables involved in this problem.
- **8.** Prove or disprove that TSP satisfies duality principle.
- **9.** What is/ are the differences between Huffman algorithm and Genetic algorithm?
- 10. Given a perimeter of length L, it is possible to draw different geometrical shapes such as triangle, circle, rectangle, pentagon etc. Out of these shapes, how you can find a shape with minimum (maximum) surface area. Can you formulate this problem as an optimization problem?
- 11. Is there any scope to apply GA to obtain an ANN architecture for a given problem? If your answer is yes, then how?
- 12. Is there any scope to apply GA in the design of a fuzzy logic controller? If yes, then explain how?
- **13.** For the following problems, precisely state the objective functions, constraints and design parameters involved. Also, for each suggest which encoding scheme you should consider to implement Genetic algorithm.
 - (a) Given a piece of cardboard of size $L \times W$. It is planned to cut out the corners as shown below and fold up the sides to form a box, also shown below. Determine the height of the box that will give maximum volume.

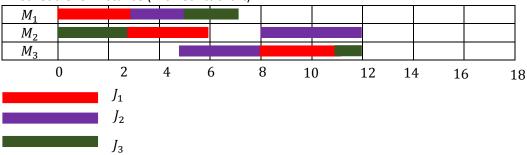


- (b) <u>Money allocation problem.</u> In an investment scenario in equity market, N different instruments are declared where an i-th instrument returns $f_i(x_i)$ on investing x_i amount in it. A customer has C amount of capital to be invested. How he should invest his capital to the N instruments to maximize his return?
- (c) <u>Job shop scheduling problem.</u> A set of n jobs $J_1, J_2, J_3, \ldots, J_n$ which are to be processed on a set of m machines $M_1, M_2, M_3, \ldots, M_n$. Each job needs a strict sequence of machines which is known to the scheduler.
 - (i) Processing a job J_i on a machine M_j requires the exclusive use of M_j for an uninterrupted duration p_{ij} , which is also known to the scheduler.
 - (ii) The time required to complete all jobs submitted to the scheduler is called *makespan*, *T*.

The objective of the scheduler is to determine schedule of jobs to machine minimizing T. A small instance of 3×3 job scheduling problem is given for your understanding.

Job		Operation(time)	
J_1	$M_1(3)$	$M_2(3)$	$M_3(3)$
J_2	$M_1(2)$	$M_3(3)$	M ₂ (4)
J_3	$M_2(3)$	$M_1(2)$	$M_3(1)$

A schedule for instance (with Gantt chart)



(d) Rod cutting problem. Given a rod of length L and it is required to be cut into maximum p pieces. The cost c_i of a piece p_i of length l_i is given.

Length, l_i	l_1	l_2		l_m
Cost, c_i	c_1	c_2	•••	c_m

Assume the cost of cutting is free. It is asked to cut the rod into a number of small pieces so that the cost of cutting ensembles is maximum.

- (e) Decide GA parameters involved different GA operators. Give a rule of thumb to decide the values of GA parameters. Also, mention how the values of GA parameters affect the performance of GA with reference to
 - (i) Rate of convergence
 - (ii) Accuracy of result
- (f) Propose the framework of GA (can be termed as Hybrid GA (HGA)) combining some strategy, taking from SGA and SSGA.
- (g) There is a factory located at each of the two places P and Q. From these locations, a certain commodity is delivered to each of the three depots situated at A, B and C. The daily requirements of the depots are a, b and c units of commodity, respectively while the production capacity of the factories at P and Q are p and q units respectively. Further, the cost of transportation from any factory to any depot is given below:

	A	В	С
P	c_{pa}	c_{pb}	c_{pc}
Q	c_{qa}	c_{qb}	c_{qc}

Formulate the above problem as an optimization problem in terms of minimum number of design parameters.

B. Introduction to GA

- 1. Which of the following statement(s) is (are) not true?
 - (a) GA is an optimization technique.
 - (b) GA is a probabilistic search technique.
 - (c) GA always gives optimal solution.
 - (d) For a problem, if there is more than one optimal solutions, GA outputs all the solutions.
- **2.** GA is effective to solve only
 - (a) Single objective optimization problems.
 - (b) Mixed integer programming problem.
 - (c) Optimization problems involved with discrete (integer) variables.
 - (d) Optimization problems involved with continuous (integer/ real) variables.
- **3.** In simple GA (SGS), which is/ are not allowed.
 - (a) Repetition in the individual selected for mating pool.
 - (b) Population sizes in each generations are to be varied.
 - (c) Overlapping generations.
 - (d) Two or more individuals with same fitness value.
- **4.** In the context of simple GA (SGA), the convergence rate will increase if
 - (a) The size of mating pool (N_p) is comparable to that of the population size (N).
 - (b) From the mating pool of size (N_p) , if we create N offspring to replace all individual in the current population.
 - (c) From the mating pool of size (N_p) , if we create a large number of offspring and replace only N_p worst individuals in the current population size (N).
 - (d) Select N_p best individuals for mating to produce N individual for the next generation.
- 5. In the context of Steady-State GA (SSGA), which of the following statement(s) is/ are true.
 - (a) Generation gap is small.
 - (b) Convergence rate is high.
 - (c) Gives better result than Simple Genetic algorithm (SGA).
 - (d) It is susceptible to stagnation.

6.	Which GA	framework is	preferable	when?

(a)	Population size is very large.	-	
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- (b) Calculation of fitness value of any individual is computationally expensive.-____
- (c) Needs to produce results with fewer cycles. -
- (d) Needs to produce move near optimum solution. -

7. If we compare SGA and SSGA, then

- (a) The time for single iteration in SGA is more than in SSGA.
- (b) Overall time for termination in SGA is more than in SSGA.
- (c) Population diversity in SGA is far better than that of SSGA.
- (d) Selection pressure in SGA is more than that of SSGA.

8. Which of the following cannot be considered as convergence criterion

- (a) There is no significant change in the average fitness value for n successive generations.
- (b) The execution of GA elapsed a pre-specified time T.
- (c) p percentage of N (where p is some positive constant and N is the size of the population) individuals are with the same fitness values.
- (d) Fitness values of all individuals are above than a certain threshold value.

1. An optimization problem is stated as follows:

maximize
$$f(x,y) = \frac{x^2}{2} + \frac{125}{y^2}$$
 where $x,y \in R^+$

The above optimization problem comes under the category of

- (a) Unconstrained optimization problem.
- (b) Linear optimization problem.
- (c) Integer value optimization problem.
- (d) Real value optimization problem.

2. Which of the following is not true for Genetic algorithms.

- (a) It is a probabilistic search algorithm.
- (b) It is guaranteed to give global optimum solutions.
- (c) If an optimization problem has more than one solution, then it will return all the solutions.

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- (d) It is an iterative process suitable for parallel programming.
- 3. Which one of the following is a faster encoding scheme?
 - Binary coded GA. (a)
 - Real coded GA. (b)
 - Order GA. (c)
 - (d) Tree encoded GA.
- 4. Which of the following optimization problem(s) can be better solved with Order GA?
 - 0-1 Knapsack problem. (a)
 - (b) Travelling salesman problem.
 - Job shop scheduling problem. (c)
 - (d) Optimal binary search tree construction problem.
- 5. Which of the following GA operator is computationally most expensive?
 - Initial population creation. (a)
 - (b) Fitness evaluation.
 - (c) Selection.
 - (d) Crossover.
- 6. For a given optimization problem, and using the same GA parameters, if a GA algorithm is executed multiple times, then
 - It will always give same solution. (a)
 - (b) It will never give same solution.
 - (c) It is likely to give same solution.
 - (d) None of the above.
- Principle of duality is related to transforming a maximization problem to minimization problem 7. and vice-versa. In this context, which of the following statements is/are true?
 - For every problem, there is a dual problem. (a)
 - (b) There exists some problems for which dual problems exist.
 - Solution of a problem P and its dual problem P' are same. (c)
 - (d) Solution of a problem P and its dual problem P' are not same.

- 8. Suppose, all steps in both SGA and SSGA remain same, except instead of selecting two individuals from the current population of size N, N_p ($N_p \ll N$) individuals as in SGA are selected. Then,
 - (a) Generation gap of SGA will be more than that of SSGA.
 - (b) Generation gap of SSGA will be more than that of SGA.
 - (c) Generation gap in both algorithms remains same.
 - (d) Nothing can be said precisely.
- 9. Genetic algorithms terminate quickly, iff
 - (a) In each iteration it maintains a large generation gap.
 - (b) In each iteration it maintains a small generation gap.
 - (c) In each iteration only best individuals are selected for mating.
 - (d) In each iteration only worst individuals are selected for mating.
- **10.** GA is preferred algorithm to solving optimization problems because
 - (a) It can be applied to any optimization problem.
 - (b) It can solve any non-polynomial time optimization problem.
 - (c) Parallel programming is possible to implement in GA.
 - (d) It gives guaranteed optimal solution within reasonable time.

C. Encoding Schemes and Crossover in GA

- 1. Which of the following statement is true?
 - Binary coded GAs are faster than real coded GAs. (a)
 - (b) Binary coded GAs are accurate than real coded GAs.
 - All optimization problems can be encoded with binary coded GA. (c)
- (d) All GA parameters, which are applicable to binary coded GA is also applicable to order GA.
- 2. The length of chromosomes in binary coded GAs is decided by
 - Number of design variables. (a)
 - (b) Range of values of design variables.
 - Objective functions. (c)
 - Constraints.
- 3. What should be the structure of chromosomes if an optimization problem is given as

 $minimize \ f_i(x_1^i,x_2^i,x_3^i,...,x_n^i) \quad \ for \ i=1,2,...,k \quad \ subject \ to \ g_j(x_i^j,x_2^j,x_3^j,...,x_n^j) \quad \ for \ j=1,2,...,k$ 1,2, ..., *l*

and x_1, x_2, \dots, x_p are the set of all design parameters.

4. Which of the following is/are not valid chromosomes in order GA?

(a)

1	0	0	1	1	0	0	1

(b)

1	3	5	7	2	4	6	1

(c)

Α	В	D	Е	Α	F	Н	G

(d)

14.6	-23.4	177.23

5.	Out of the	following	crossover	techniques	which	do(es)	not	suffer(s)	from	"end	point	bias"
	problem?											

- (a) Single point crossover.
- (b) Uniform crossover.
- (c) Shuffle crossover.
- (d) Multipoint crossover.
- 6. Hamming distance problem in crossover techniques never occur in
 - Binary coded GA. (a)
 - (b) Real coded GA.
 - Order GA. (c)
 - (d) Tree encoded GA.
- 7. Which of the following crossover techniques in order GA suffers from "position bias" proble?
 - (a) Single point order crossover.
 - (b) Precedence preservative order crossover.
 - Position based crossover. (c)
 - (d) Edge recombination crossover.
- 8. Which of the following crossover technique is known for real coded GA?
 - Half uniform crossover. (a)
 - (b) Simulated binary crossover.
 - (c) Three parent crossover.
 - Position based crossover. (d)
- 9. State whether the following statements are true or false.
 - (a) The most expensive operation in GA is the selection of individual for mating pool creation.
 - (b) Mutation operation is not mandatory in any GA based problem solving.
 - (c) The number of GA loop will increase if the population size is increased.
 - (d) Even we can implement Simple GA without performing selection operation.

- 10. This is with reference to the **Problem A. 13(g)**. It is proposed to solve the said optimization problem using Binary coded GA. Decide the genotype for the chromosome structure to do this.
 - Suppose the problem needs to be adapted with m factories and n destinations. What changes in chromosome structure you should devise?

D. Selection operations in GA

- **11.** The purpose of the fitness evaluation operation is
 - (a) To check whether all individuals satisfies the constraints given in the problem.
 - (b) To decide the termination point.
 - (c) To select the best individuals.
 - (d) To identify the individual with worst cost function.
- **12.** Average fitness calculation can be used to
 - (a) Understand whether the optimal solution(s) has been achieved.
 - (b) Termination of GA execution.
 - (c) Generation gap between two successive GA iteration.
 - (d) Whether the problem has been stuck at local optima or not.
- **13.** Roulette wheel selection scheme is preferable when
 - (a) Fitness values are uniformly distributed.
 - (b) Fitness values are non-uniformly distributed.
 - (c) Needs low selection pressure.
 - (d) Needs high population diversity.
- **14.** Which of the following operation(s) is (are) more computationally expensive
 - (a) Roulette wheel selection.
 - (b) Rank based selection.
 - (c) Tournament selection.
 - (d) Steady state selection.
- **15.** Which of the following selection scheme may select an individual more than once
 - (a) Roulette wheel selection.
 - (b) Rank based selection.
 - (c) Tournament selection.
 - (d) Steady state selection.

- **16.** Which of the following statement is true in case of Rank based selection scheme
 - (a) Low population diversity, high selection pressure.
 - (b) Low population diversity, low selection pressure.
 - (c) High population diversity, low selection pressure.
 - (d) High population diversity, high selection pressure.
- 17. High selection pressure is desirable when we need
 - (a) Faster termination of GA.
 - (b) Near optimal solution.
 - (c) There is no improvement in successive GA iteration.
 - (d) Fitness values are non-uniformly distributed.
- **18.** Tournament selection scheme is more preferable when
 - (a) Population are with very diversified fitness values.
 - (b) When fitness values are uniformly distributed.
 - (c) When fitness values are not necessarily uniformly distributed.
 - (d) Under all the above situations.
- 19. To make the generation gap (G_p) in a Steady state selection strategy a large value, which of the following can be considered?
 - (a) Selection of individuals according to their fitness values and replacement at random.
 - (b) Selection of individuals at random and replacement according to the inverse of their fitness values.
 - (c) Selection of both parents and replacement according to the inverse of their fitness values.
 - (d) All of the above.
- **10.** Answer the following:
 - (a) Precisely state the two major steps in Tournament selection strategy.
 - (b) How Tournament selection strategy is comparable to Roulette wheel selection strategy?
 - (c) It is planned to apply Roulette wheel selection scheme into Tournament selection strategy. Give your idea to do this.

- (d) Define population diversity and selection pressure.
- (e) Give your idea to measure the above two while GA is in execution.
- (f) Is there any relation between the two?
- (g) How population diversity (or selection pressure) can be controlled?
- (h) As GA leads to termination, population diversity decreases while selection pressure increases.
- (i) How the two measure can be considered to decide a termination criterion?